[1] - I. S. Sarwar and A. M. Malik, "Stability analysis and simulation of a two DOF robotic system based on linear control system," 2008 15th International Conference on Mechatronics and Machine Vision in Practice, Auckland, 2008, pp. 263-268

[2] - I. S. Sarwar and A. M. Malik, "Modeling, analysis and simulation of a Pan Tilt Platform based on linear and nonlinear systems," 2008 IEEE/ASME International Conference on Mechtronic and Embedded Systems and Applications, Beijing, 2008, pp. 147-152

[3] - Sarwar, Imran & Iqbal, Javaid & Malik, Afzaal. (2009). Modeling, analysis and motion control of a pan tilt platform based on linear and nonlinear systems. WSEAS Transactions on Systems and Control. 4. 389-398

[4] - A. K. Pandey and M. Mittal, "Analysis of a robotic system with two DOF using Haar wavelet," 2014 IEEE 6th India International Conference on Power Electronics (IICPE), Kurukshetra, 2014, pp. 1-5

[5] - Yihui Fan et al 2019 J. Phys.: Conf. Ser. 1267 012086

[6] - ATUL KUMAR PANDEY, and MONIKA MITTAL. "OPTIMAL CONTROL OF A ROBOTIC SYSTEM WITH TWO DEGREE OF FREEDOM”, International Journal of Electrical and Electronics Engineering (IJEEE), Vol. 4, Issue 6, Oct – Nov 2015, 1-10  
© IASET